

COSC160: Data Structures Graph Theory

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Outline

A graph is a discrete structure representing adjacency relations

- We start with definitions:
 - Vertices, edges, degree and sub-graphs
- We will describe paths in graphs
 - Simple paths and cycles
- Definition of connectedness
- Weighted graphs
- We will then reinterpret these in terms of directed graphs
- Directed acyclic graphs



Outline

We will define an Undirected Graph as a collection of *vertices and edges*

$$V = \{v_1, v_2, ..., v_n\}$$

- The number of vertices is denoted by

|V| = n

- Associated with this is a collection *E* of <u>unordered</u> pairs $\{v_i, v_j\}$ termed *edges* which connect the vertices

There are a number of data structures that can be used to implement abstract undirected graphs

- Adjacency matrices
- Adjacency lists



Graphs

Consider this collection of vertices

$$V = \{v_1, v_2, ..., v_9\}$$

where |V| = n





Undirected graphs

Associated with these vertices are |E| = 5 edges

 $E = \{ \{v_1, v_2\}, \{v_3, v_5\}, \{v_4, v_8\}, \{v_4, v_9\}, \{v_6, v_9\} \}$

- The pair $\{v_j, v_k\}$ indicates that both vertex v_j is adjacent to vertex v_k and vertex v_k is adjacent to vertex v_j





Undirected graphs

We will assume in this course that a vertex is never adjacent to itself

- For example, $\{v_1, v_1\}$ will not define an edge

$$|E| \leq \binom{|V|}{2} = \frac{|V|(|V|-1)}{2} = O(|V|^2)$$

The maximum number of edges in an undirected graph is



An undirected graph

Example: given the |V| = 7 vertices

 $V = \{A, B, C, D, E, F, G\}$

and the |E| = 9 edges

 $E = \{\{A, B\}, \{A, D\}, \{A, E\}, \{B, C\}, \{B, D\}, \{B, E\}, \{C, E\}, \{C, F\}, \{D, E\}\}$





Degree

The degree of a vertex is defined as the number of adjacent vertices



Those vertices adjacent to a given vertex are its *neighbors*



Sub-graphs

A *sub-graph* of a graph a subset of the vertices and a subset of the edges that connected the subset of vertices in the original graph







Vertex-induced sub-graphs

A vertex-induced sub-graph is a subset of a the vertices where the edges are all edges in the original graph that originally







A path in an undirected graph is an ordered sequence of vertices

 $(v_0, v_1, v_2, ..., v_k)$

where $\{v_{j-1}, v_j\}$ is an edge for j = 1, ..., k

- Termed *a path from* v_0 to v_k
- The length of this path is k



A path of length 4: (A, B, E, C, F)





A path of length 5: (A, B, E, C, B, D)





A *trivial* path of length 0:

(A)





Simple paths

A *simple path* has no repetitions other than perhaps the first and last vertices

A *simple cycle* is a simple path of at least two vertices with the first and last vertices equal

– Note: these definitions are not universal



Connectedness

Two vertices v_i , v_j are said to be *connected* if there exists a path from v_i to v_j

A graph is connected if there exists a path between any two vertices





A weight may be associated with each edge in a graph

- This could represent distance, energy consumption, cost, etc.
- Such a graph is called a *weighted graph*

Pictorially, we will represent weights by numbers next to the edges $A_{2.5} = B_{3.5}$





The *length* of a path within a weighted graph is the sum of all of the edges which make up the path

- The length of the path (A, D, G) in the following graph is 5.1 + 3.7 = 8.8





Different paths may have different weights

- Another path is (A, C, F, G) with length 1.2 + 1.4 + 4.5 = 7.1





Problem: find the shortest path between two vertices

– Here, the shortest path from A to H is (A, C, F, D, E, G) with length 5.7





Trees

A graph is a tree if it is connected and there is a unique path between any two vertices

- Three trees on the same eight vertices



Consequences:

- The number of edges is |E| = |V| 1
- The graph is *acyclic*, that is, it does not contain any cycles
- Adding one more edge must create a cycle
- Removing any one edge creates two disjoint non-empty sub-graphs



Trees

Any tree can be converted into a rooted tree by:

- Choosing any vertex to be the root
- Defining its neighboring vertices as its children

and then recursively defining:

 All neighboring vertices other than that one designated its parent are now defined to be that vertices children

Given this tree, here are three rooted trees associated with it



Forests

A forest is any graph that has no cycles

Consequences:

- The number of edges is |E| < |V|
- The number of trees is |V| |E|
- Removing any one edge adds one more tree to the forest

Here is a forest with 22 vertices and 18 edges

- There are four trees

Directed graphs

In a *directed graph*, the edges on a graph are be associated with a direction

- Edges are ordered pairs (v_i, v_k) denoting a connection from v_i to v_k
- The edge (v_j, v_k) is different from the edge (v_k, v_j)

Streets are directed graphs:

- In most cases, you can go two ways unless it is a one-way street



Directed graphs

Given our graph of nine vertices $V = \{v_1, v_2, ..., v_9\}$

- These six pairs (v_i, v_k) are directed edges

 $E = \{(v_1, v_2), (v_3, v_5), (v_5, v_3), (v_6, v_9), (v_8, v_4), (v_9, v_4)\}$





Directed graphs

The maximum number of directed edges in a directed graph is

$$|E| \le 2\binom{|V|}{2} = 2\frac{|V|(|V|-1)}{2} = |V|(|V|-1) = O(|V|^2)$$



In and out degrees

The degree of a vertex must be modified to consider both cases:

- The *out-degree* of a vertex is the number of vertices which are adjacent to the given vertex
- The *in-degree* of a vertex is the number of vertices which this vertex is adjacent to v_1

In this graph: in_degree(v_1) = 0 out_degree(v_1) = 2 in_degree(v_5) = 2 out_degree(v_5) = 3



Sources and sinks

Some definitions:

- Vertices with an in-degree of zero are described as sources
- Vertices with an out-degree of zero are described as *sinks*

In this graph:

- Sources: v_1, v_6, v_7
- **–** Sinks: v_2 , v_9



A path in a directed graph is an ordered sequence of vertices

 $(v_0, v_1, v_2, ..., v_k)$ where (v_{j-1}, v_j) is an edge for j = 1, ..., k

A path of length 5 in this graph is $(v_1, v_4, v_5, v_3, v_5, v_2)$

A simple cycle of length 3 is (v_8, v_4, v_5, v_8)



Connectedness

Two vertices v_j , v_k are said to be *connected* if there exists a path from v_j to v_k

- A graph is strongly connected if there exists a directed path between any two vertices
- A graph is *weakly connected* there exists a path between any two vertices that ignores the direction v_2

In this graph:

- The sub-graph $\{v_3, v_4, v_5, v_8\}$ is strongly connected
- The sub-graph $\{v_1, v_2, v_3, v_4, v_5, v_8\}$ is weakly connected



Weighted directed graphs

In a weighted directed graphs, each edge is associated with a value

Unlike weighted undirected graphs, if both (v_j, v_k) and (v_j, v_k) are edges, it is not required that they have the same weight



Directed acyclic graphs

A directed acyclic graph is a directed graph which has no cycles

- These are commonly referred to as DAGs
- They are graphical representations of partial orders on a finite number of elements

These two are DAGs:



This directed graph is not acyclic:





Representations

How do we store the adjacency relations?

- Binary-relation list
- Adjacency matrix
- Adjacency list



Binary-relation list

The most inefficient is a relation list:

A container storing the edges

 $\{(1, 2), (1, 4), (3, 5), (4, 2), (4, 5), (5, 2), (5, 3), (5, 8), (6, 9), (7, 9), (8, 4)\}$

- Requires $\Theta(|E|)$ memory
- Determining if v_j is adjacent to v_k is O(|E|)
- Finding all neighbors of v_i is $\Theta(|E|)$



Adjacency matrix

Requiring more memory but also faster, an adjacency matrix – The matrix entry (j, k) is set to true if there is an edge (v_j, v_k)



Adjacency list

Most efficient for algorithms is an adjacency list

- Each vertex is associated with a list of its neighbors

 $1 \quad \bullet \rightarrow 2 \rightarrow 4$ $2 \quad \bullet$ $3 \quad \bullet \rightarrow 5$ $4 \quad \bullet \rightarrow 2 \rightarrow 5$ $5 \quad \bullet \rightarrow 2 \rightarrow 3 \rightarrow 8$ $6 \quad \bullet \rightarrow 9$ $7 \quad \bullet \rightarrow 9$ $8 \quad \bullet \rightarrow 4$ $9 \quad \bullet$

- Requires $\Theta(|V| + |E|)$ memory
- On average:
 - Determining if v_j is adjacent to v_k is $O\begin{pmatrix} |E| \\ |V| \end{pmatrix}$
 - Finding all neighbors of v_j is $\Theta \begin{pmatrix} |E| \\ \end{pmatrix}$



The Graph ADT

The Graph ADT Design Idea... a container storing an adjacency relation

- Queries include:
 - The number of vertices
 - The number of edges
 - List the vertices adjacent to a given vertex
 - Are two vertices adjacent?
 - Are two vertices connected?
- Modifications include:
 - Inserting or removing an edge
 - Inserting or removing a vertex (and all edges containing that vertex)

The run-time of these operations will depend on the representation



Summary

In this topic, we have covered:

- Basic graph definitions
 - Vertex, edge, degree, adjacency
- Paths, simple paths, and cycles
- Connectedness
- Weighted graphs
- Directed graphs
- Directed acyclic graphs

Moving forward, we will investigate a number of problems related to graphs





Appendix

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Spanning Trees

- Idea: Given a graph, produce a subgraph that is a tree (that connects all nodes with n-1 edges)
- Algorithms
 - Kruskals Algorithm
 - Prim's Algorithm

