



COSC160: Data Structures Trees

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Outline

I. Trees

I. Terminology

II. Traversals

I. DFS

I. InOrder

II. PreOrder

III. PostOrder

II. BFS

III. Pseudocode Examples

Trees

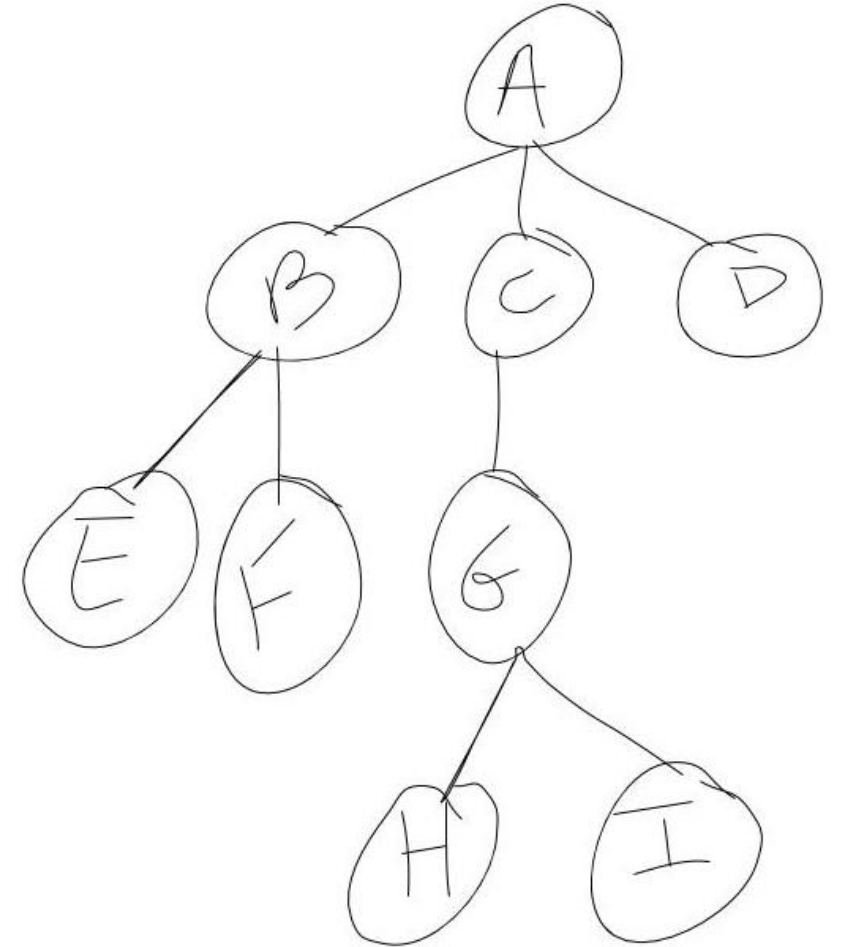
- A tree is a fundamental discrete structure used in computer science.
 - In computer science we are generally interested in *rooted* trees. Henceforth when we will refer to all rooted trees simply as trees.
 - Uses: compiler design, file hierarchy representation, data organization, ...

Trees

- Definitions:
 - A node is an entity, visually displayed as a circle, that may have a name and attributes.
 - A directed edge is a 2-tuple, e.g. $\text{edge1} = (\text{node1}, \text{node2})$, that is said to connect two nodes. The edge is directed and so, node1 is connected to node2 but the reverse may not be so.
 - A path of length n between node i and node j is a sequence of edges where the first element of edge 1 is node i , the second element of edge n is node j , all neighboring edges in the sequence share the same connecting node.
 - EG Path from node 1 to node 5 of length 3: $(1,2) (2,4) (4,5)$
 - A (rooted) tree is a set of nodes and a set of directed edges with the following properties
 - One node is designated as the root
 - There is no path from any node (that is not the root) to the root node.
 - There is a unique *path* between the root node and each node.

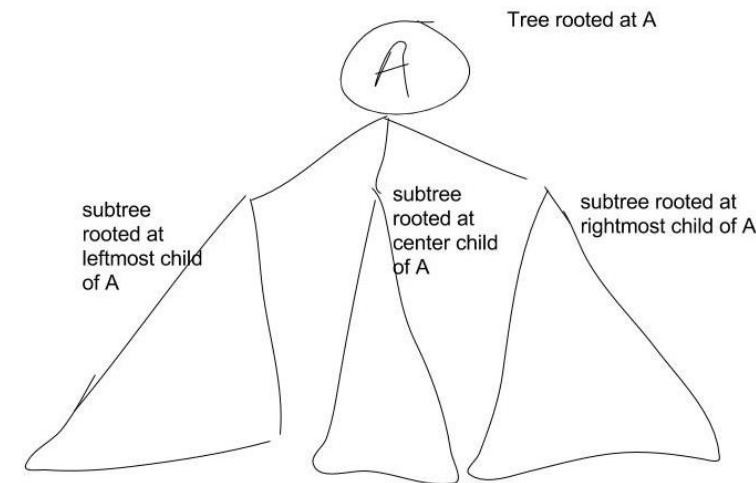
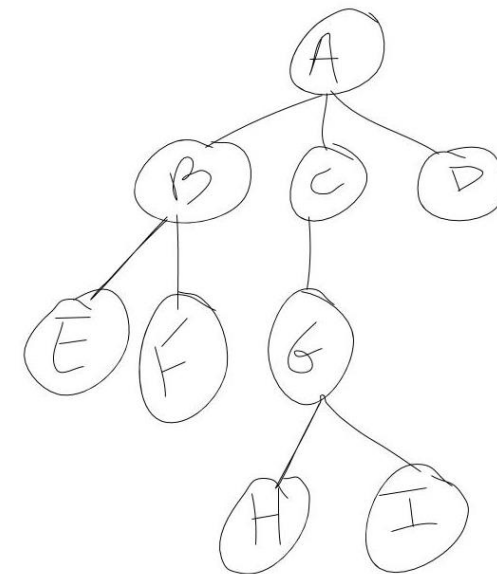
Trees: terminology

- A directed edge connects a parent node and a child node
 - EG, assume edge = (node A , node B). A is the parent of B and B is the child of A.
 - Observations:
 - The root node has no parent.
 - Nodes that have no children are called *leaves*.
 - Nodes that share a parent are called *siblings*
 - If there is a path from node i to node j, then i is an ancestor of j and j is a descendent of i.
- The depth of a node j is the length of the path from the root to node j
 - The root node is at depth 0.
 - The depth of any node j is equal to the depth of the parent of node j + 1
 - The height of the tree is equal to the maximum depth over all nodes in the tree.



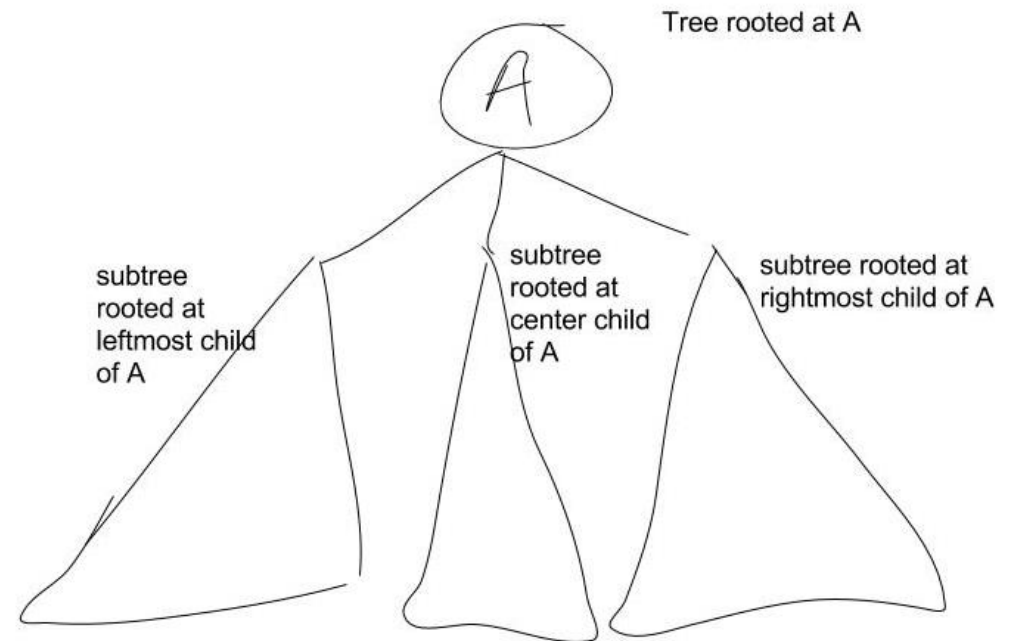
Recursive Definition of Trees

- The following are trees (shown as a set of nodes and set of edges)
 - The empty tree. No nodes, no edges
 - $(\{\}, \{\})$
 - A (root) node
 - $(\{n_1\}, \{\})$
 - If T_1 and T_2 are two trees, then T_3 , formed by connecting any node from T_1 to the root node of T_2 , is a tree.
 - $T_1 = (N_1, E_1)$
 - $T_2 = (N_2, E_2)$
 - $T_3 = (N_3, E_3)$,
 - where $N_3 = N_1 \cup N_2$
 - $E_3 = E_1 \cup E_2 \cup \{e\}$, where $e = (n_1, r_2)$ where $n_1 \in N_1$ and $r_2 \in N_2$ and r_2 is the root of T_2
 - Observe: root of tree 1 is the root of tree 3

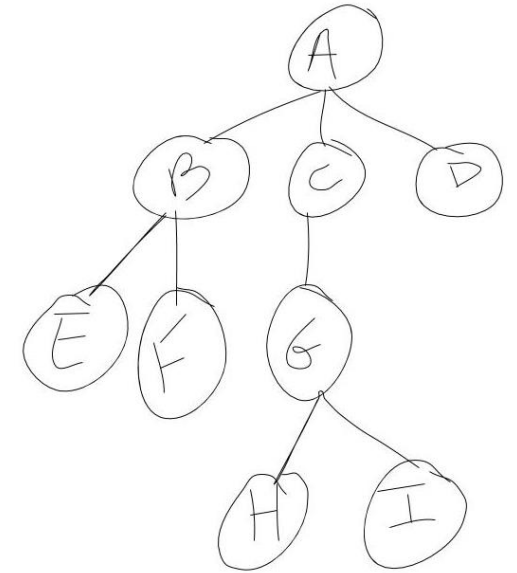


Subtrees

- A subtree st of a tree t is a tree whose set of nodes and edges are subsets of $(n,e) = t$.
 - $st = (N_1, E_1)$, where $t = (N, E)$, where $N_1 \subseteq N$ and $E_1 \subseteq E$ AND st is a tree.
- Given the recursive definition of trees observe the following:
 - All nodes in a tree are a root of a subtree



Tree Implementation (version 1)



- Designing a generic tree structure
 - Design concern: the number of children for any parent is unknown and may change dynamically (depending on usage).
 - Basic Design Option (list of children implementation):
 - Node class
 - Attributes include: data, listOfChildren
 - Tree class
 - Attributes include: rootNode
 - How can we design a list of children that is variable in size (between nodes) and may change in size?
 - Implement listOfChildren as Linked List

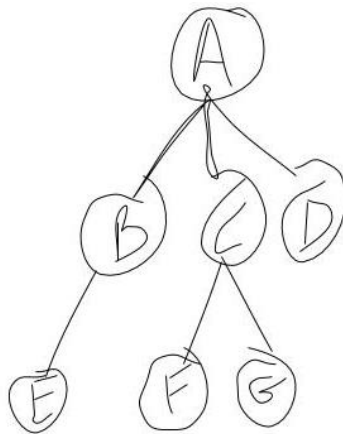
Tree <T>
+ Node* Root
+ search(<T> item): Node* + insert(<T> item): void + remove(<T> item): void

Node <T>
+ Node* childList + <T> Data

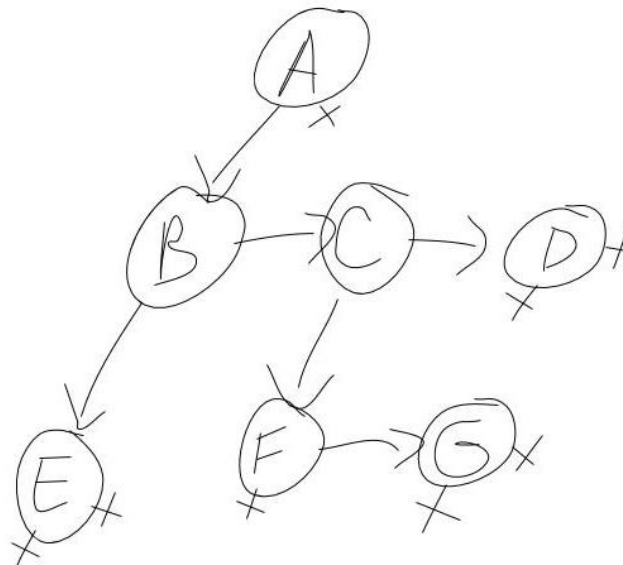
Tree Implementation (version 2)

- Rather than implementing a linked list of children, we can make the “number” of attributes for each node constant. “Alleviates” allocation concerns related to variable number of children per node.
 - left child / right sibling implementation
 - Instead of listOfChildren as a linked list, create a node class that has the following attributes
 - Node class
 - » Attributes include: data, leftMostChild, rightSibling

Actual Tree



Left Child / Right Sibling Representation



Node <T>
+ Node* leftChild
+ Node* rightSibling
+ <T> Data

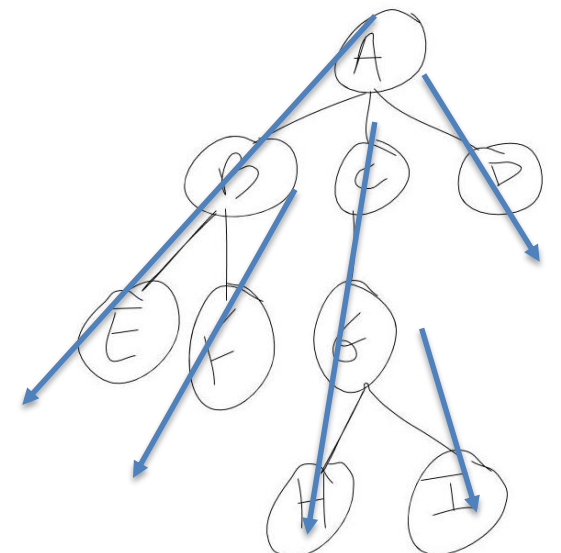
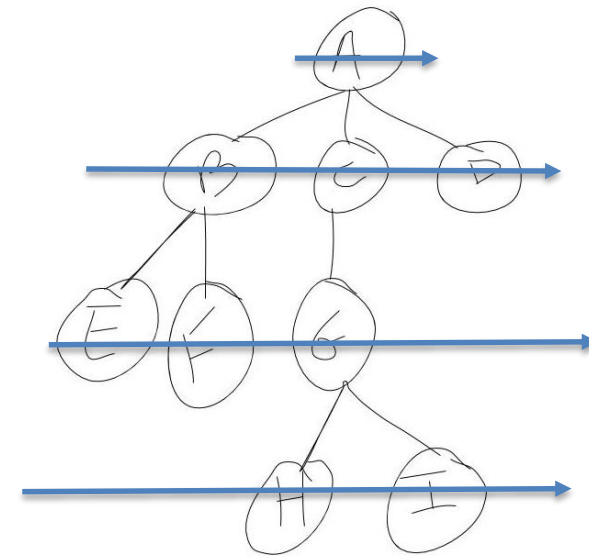
Tree Traversals

- Traversing structures

- Designing a traversal strategy is important for any data structure.
 - Visiting each element of a structure for processing, searching, ...
 - EG Lists: sequential, divide and conquer traversal, ...

- Traversing Trees (common approaches)

- Breadth First Traversal (level-order traversal): traversing a tree node-by-node in order of depth.
 - Favors breadth
- Depth First Traversal: traversing a tree node-by-node, starting at the root and proceeding as quickly as possible to the leaves.
 - Favors depth
- By standard, both traversal types traverse children in left to right order



Depth First Search (traversal)

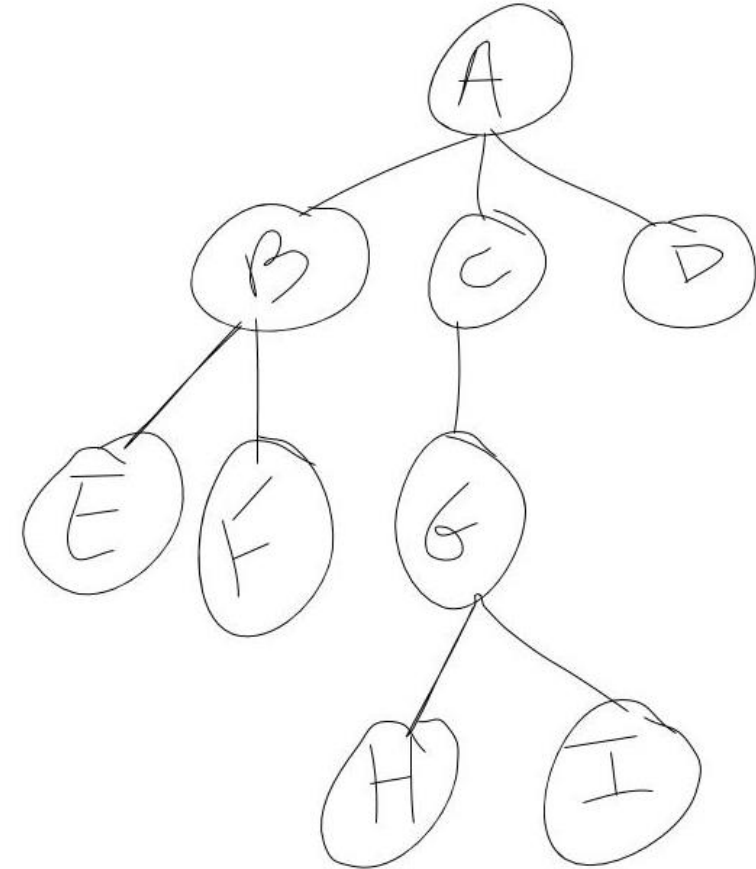
- Pseudo code

Algorithm 1

Require: keyword 'this' is used to refer to calling Tree object

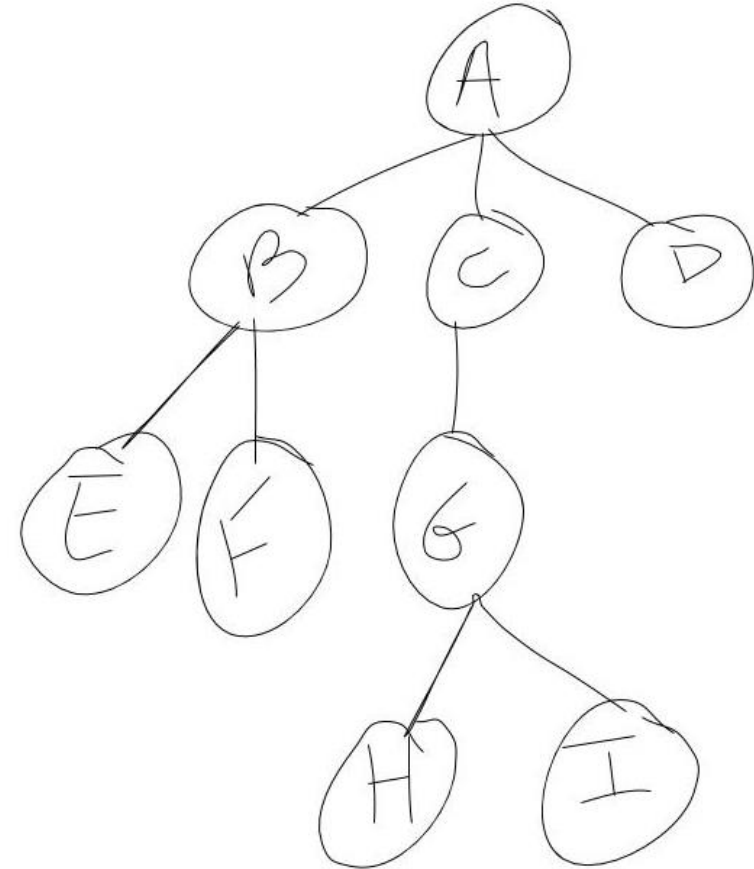
```
function DFS(Tree this)
  stack ← initialize new Stack
  stack.push(this → root)
  while ¬stack.isEmpty() do
    thisNode ← stack.pop()
    // Process thisNode Here
    for  $\forall e \in (thisNode \rightarrow childList)$  do
      stack.push(e)
```

- Try Example



DFS: recurrence perspective

- Given our recursive definition of a tree, it should come as no surprise that we can define operations on a tree (such as a traversal), recursively.
- Recurrence Idea
 - To perform a DFS on a tree with root r , perform a DFS on each subtree rooted by each child c .



DFS (recursive)

- Pseudo code
- Note: stack is implicit

Algorithm 1

Require: recursive function initially called with root as parameter

```
function DFS(Node* thisNode)
```

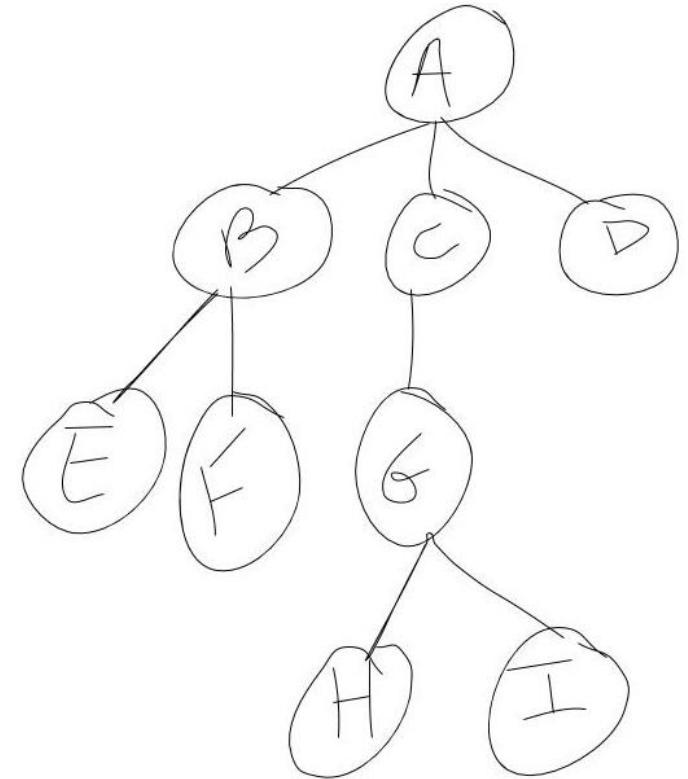
```
  // Process thisNode here for preorder traversal
```

```
  for  $\forall c \in (thisNode \rightarrow childList)$  do
```

```
    DFS(c)
```

```
  // Process thisNode here for postorder traversal
```

- Try Example



Breadth First Search (traversal)

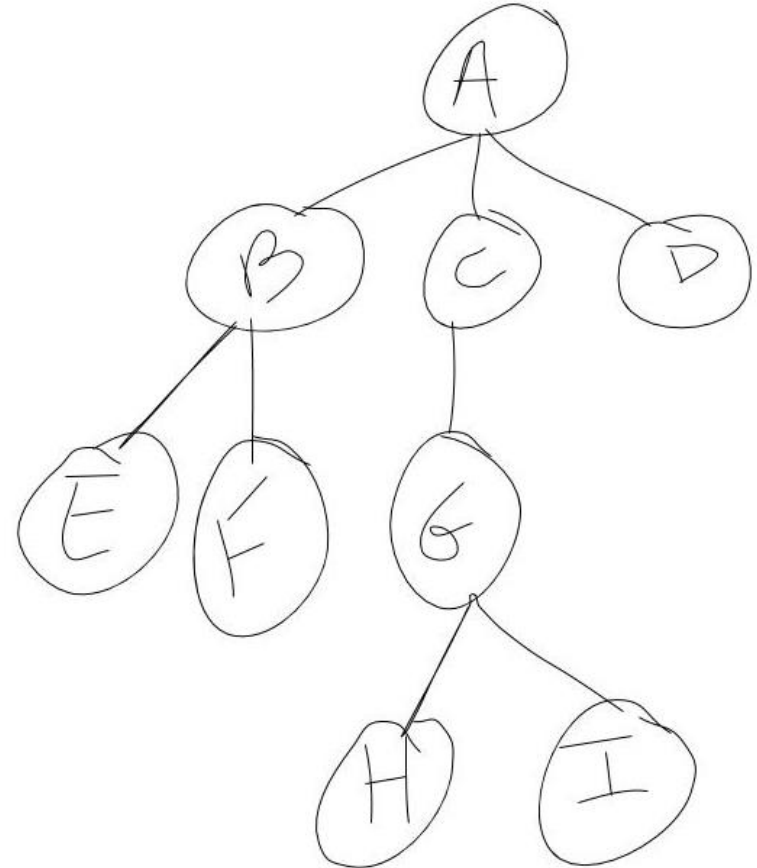
- Pseudo code

Algorithm 1

Require: keyword `this` refers to calling Tree object

```
function DFS(Tree this)
  q ← initialize new fifoQueue
  q.enqueue(this → root)
  while ¬q.isEmpty() do
    thisNode ← q.dequeue()
    // Process thisNode here
    for  $\forall c \in (thisNode \rightarrow childList)$  do
      q.enqueue(c)
```

- Try Example



Observations concerning DFS and BFS

- Observation: DFS lends itself to a simple recursive implementation. Why?
 - DFS makes use of a stack.
 - BFS makes use of a queue (FIFO).
 - A recursive, function call chain implicitly makes use of a stack (the runtime stack!)
 - Thus a recursive implementation is befitting (has a simple implementation)

DFS forms

- Common types of traversals

- Prefix / Pre-order

- A node is processed before processing its children
 - Example use: copy tree

- Infix / In-order

- A node is processed after j of its children are processed, where, in general, j is greater than 1 and less than the total number of children.
 - Example use: parser

- Postfix / Post-order

- A node is processed after all of its children are processed
 - Example use: deallocate tree

Pre-order

- Recursive Pseudo code

Algorithm 1

Require: recursive function initially called with root as parameter

function DFS(Node* thisNode)

 // Process thisNode here for preorder traversal

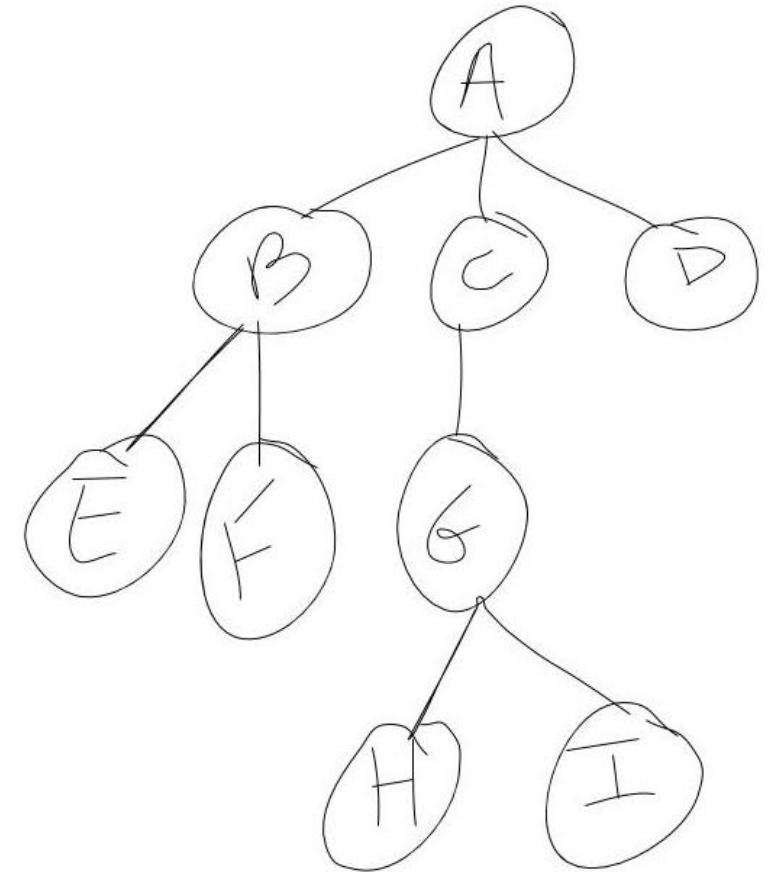
for $\forall c \in (\text{thisNode} \rightarrow \text{childList})$ **do**

 DFS(c)

 // Process thisNode here for postorder traversal

- Try Example:

A-B-E-F-C-G-H-I-D



In-order

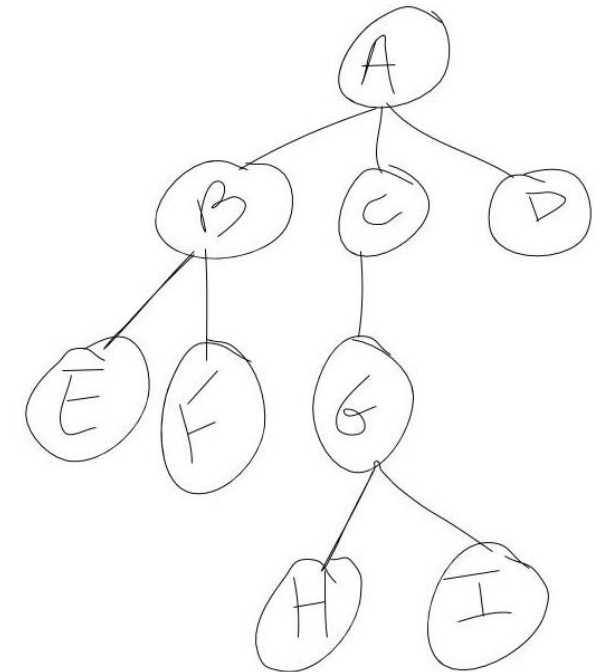
- Pseudo code for inorder traversal. Process node after visiting left child

Algorithm 1

Require: recursive function initially called with root as parameter

```
function DFS(Node* thisNode)
    // Process thisNode here for preorder traversal
    for  $\forall c \in (thisNode \rightarrow childList)$  do
        DFS(c)
    // Process thisNode here for postorder traversal
```

- Try Example
E-B-F-A-H-G-I-C-D



Post-order

- Pseudo code for postorder traversal. Process node after visiting all children nodes

Algorithm 1

Require: recursive function initially called with root as parameter

```
function DFS(Node* thisNode)
```

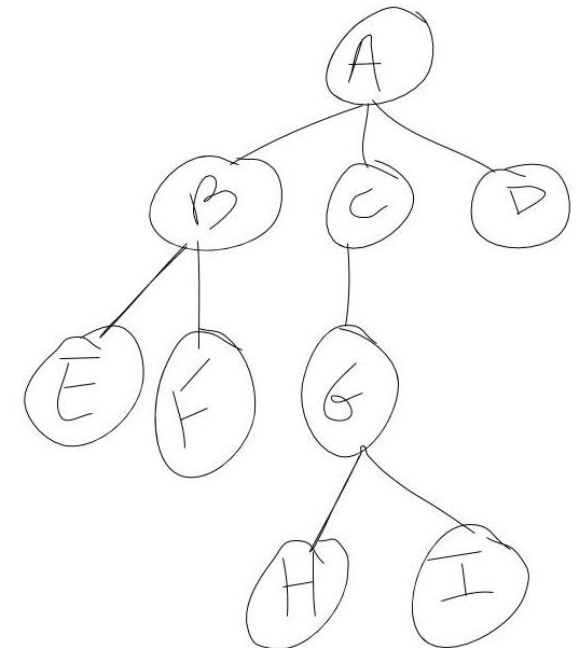
```
    // Process thisNode here for preorder traversal
```

```
    for  $\forall c \in (thisNode \rightarrow childList)$  do
```

```
        DFS(c)
```

```
    // Process thisNode here for postorder traversal
```

- Try Example
E-F-B-H-I-G-C-D-A



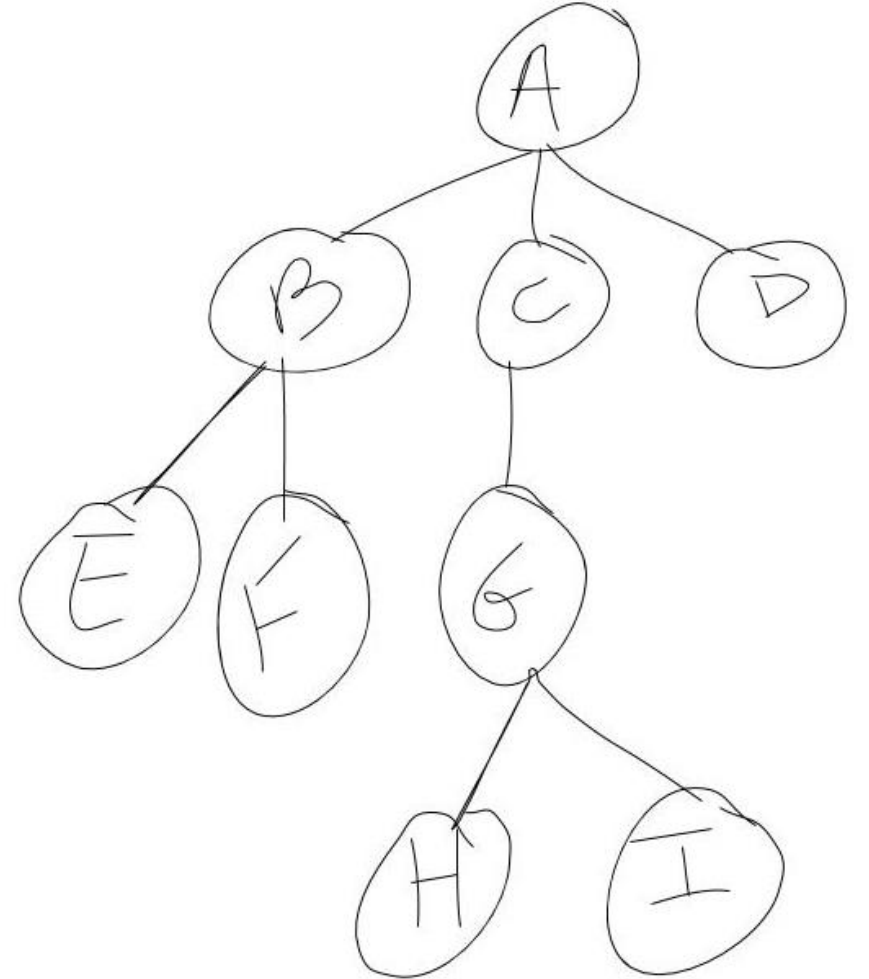
Example Use

- Copy tree intuitively implements a preorder traversal

Algorithm 1

Require: initially `thisNode` is assumed root of a tree

```
function COPYTREE(Node* thisNode)
  newNode ← newNode(thisNode → data)
  for  $\forall c \in (thisNode \rightarrow childList)$  do
    newNode.addToChildList(copyTree(c))
  return newNode
```



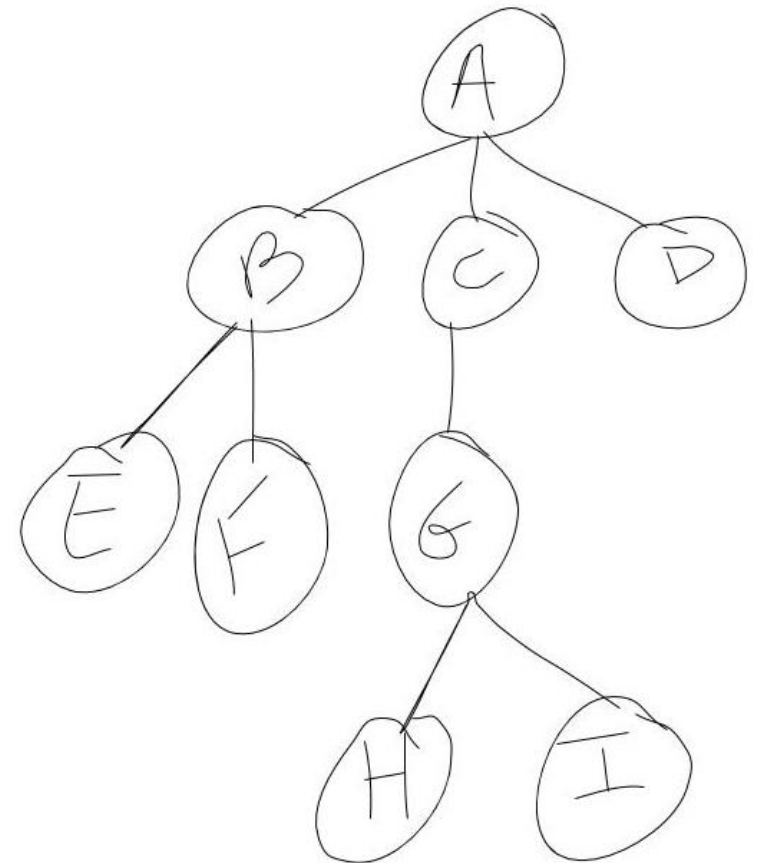
Example Use

- Dealocate tree intuitively implements a postorder traversal

Algorithm 1

Require: initially *thisNode* is assumed root of a tree

```
function DELETETREE(Node* thisNode)  
  for  $\forall e \in (\textit{thisNode} \rightarrow \textit{childList})$  do  
    deleteTree(e)  
  delete thisNode
```



Other examples

- As a practice exercise implement methods for the following:
 - Determine height of tree
 - Count number of elements
 - Make copy or delete
- Next Binary Trees
 - Similar to generic tree with extra constraint that each node has a maximum of two children, by standard, leftChild and rightChild.