

# *COSC579: Computer Vision*

Jeremy Bolton, PhD

Assistant Teaching Professor

A very special thanks to those who have contributed to this area of research over the years. Some slides used are from their research and efforts: the following professor and researchers Yung-Yu Chuang, Fredo Durand, Alexei Efros, William Freeman, James Hays, Svetlana Lazebnik, Andrej Karpathy, Fei-Fei Li, Srinivasa Narasimhan, Silvio Savarese, Steve Seitz, Noah Snavely, Richard Szeliski, and Li Zhang.

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# *Outline*

- I. Welcome!
- II. Course Overview and Administration
- III. Topics and Goals
- IV. Fun Examples

*Welcome!*

COSC-579: Computer Vision

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Assistant Teaching Professor

Department of Computer Science

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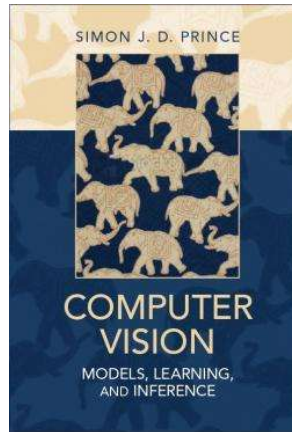
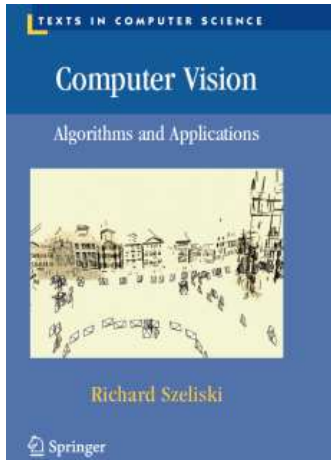
**Office Hours:** Daily hours will be entered on Canvas calendar  
(or by appointment)

**TAs:** TBD (see Canvas calendar for office hours)

# Course Summary

- **Course Description:** This course provides a comprehensive introduction to computer vision including image acquisition, low-level vision, and high-level vision. Image acquisition topics may include camera geometry, radiometry, illumination, noise, stereopsis, and affine transformations. Low-level vision topics may include, convolution, Fourier Transform, filters, operators, and feature generation. High-level vision topics may include detection, classification, segmentation, spatial relations, spatio-temporal models, object tracking, deformable models, and graph-based models.
- **Required Prerequisites:** Mathematical Statistics and Linear Algebra
- *Some existing knowledge of Machine Learning and Image Processing is preferable, but a brief review will be provided.*

# Texts



- Szeliski, Computer Vision: Algorithms and Applications, Springer, 2010
  - <http://szeliski.org/Book/>
- Prince, Computer Vision: Models, Learning, and Inference, Cambridge, 2012
  - [www.computervisionmodels.com](http://www.computervisionmodels.com)
- Goodfellow, Bengio and Courville, Deep Learning, MIT Press, 2016.
  - <http://www.deeplearningbook.org>
- Nielsen, Neural Networks and Deep Learning, 2015.
  - <http://neuralnetworksanddeeplearning.com/>
- Horn, Berthold K.P. Robot Vision. The MIT Press, 1986.

## Other References

- Forsyth and Ponce, Computer Vision: A Modern Approach, Prentice Hall, 2011.
- Bishop, Pattern Recognition and Machine Learning, Springer 2006.
- Vapnik, Statistical Learning Theory, Wiley, 2006.
- Duda, Hart, Stork, Pattern Classification, 2<sup>nd</sup> edition, Wiley, 2000.

## *Course Website*

- Link can also be found on Canvas or my department page.

<http://jeremybolton.georgetown.domains/courses/cv/>

## *Exercises and Final Project*

- **Exercises**
  - Theory (math and stats) and Application (coding).
- **Final Project: Implement Computer Vision Solution**
  - Report
  - Presentation

# *Notes about Coding*

- **Recommended Languages: Matlab or Python**
  - Request approval for use of another language.
- Coding Exercises are an integral part of this course! It is assumed that you have a proficient understanding of a programming language. Students are responsible for learning and/or reviewing, as needed, the programming language chosen.
- Matlab and Python have many packages which perform Computer Vision tasks. Depending on the exercise, you may or may not be permitted to use these built-ins (pre-existing code). Details will be provided in exercise instructions. If you have any questions about a built-in, simply ask.
- Cheating will not be tolerated. Any form of cheating will be reported to the GU honor council. Please read the following guidelines for project submissions:
  - Discussion among students pertaining to project content and general methodology is encouraged; however, students are NOT PERMITTED to share code, copy code, or use code composed by others.
  - A student may be asked to present, demonstrate, or explain a project submission at any time, without notice. At my sole discretion, a student's project grade can be adjusted based on this presentation, demonstration, and/or explanation. If a student does not sufficiently understand or explain their submission, further action may be taken.
  - Due Dates will be posted in Canvas or announced in class.



# *A Picture is Worth 100 Words*

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# *A Picture is Worth 10,000 Words*

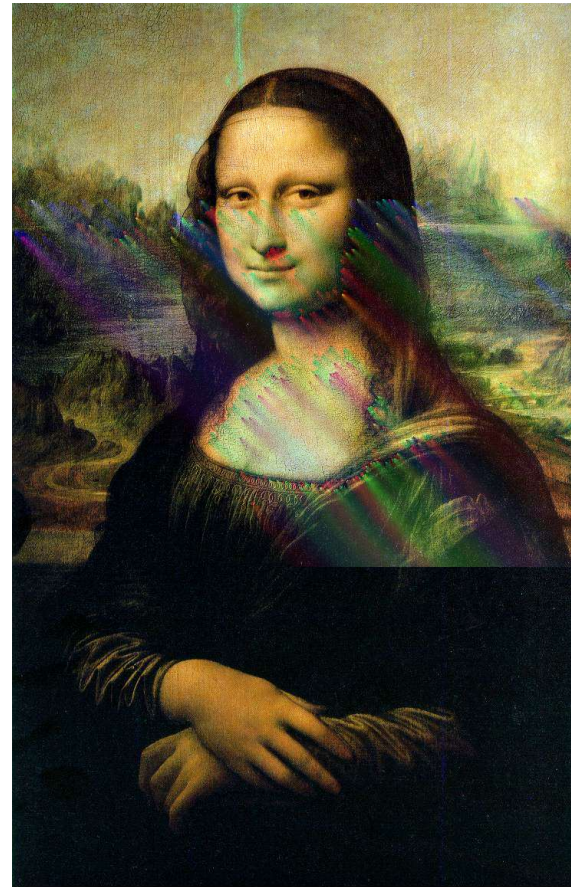
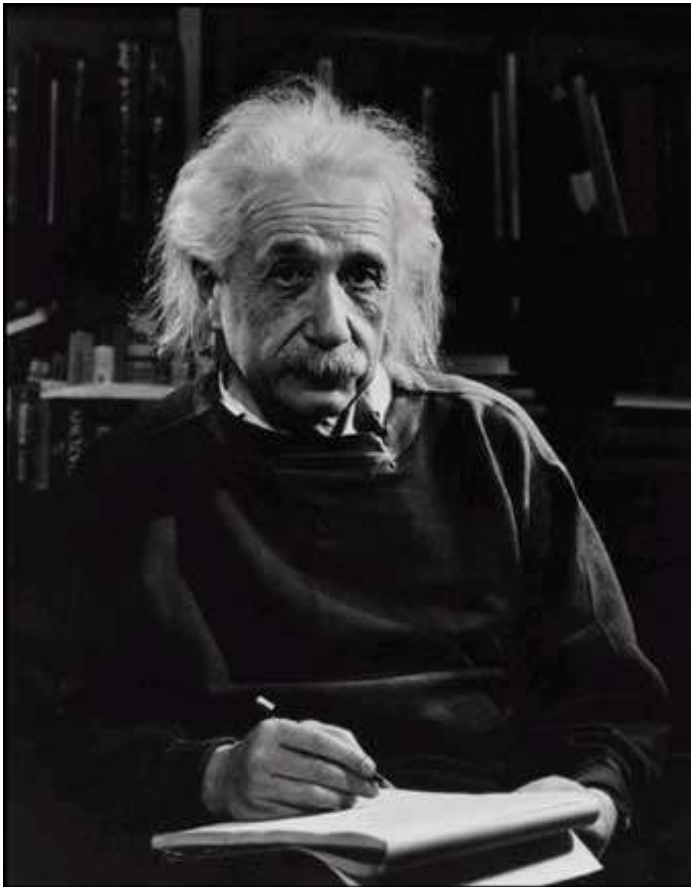
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# *A Picture is Worth a Million Words*

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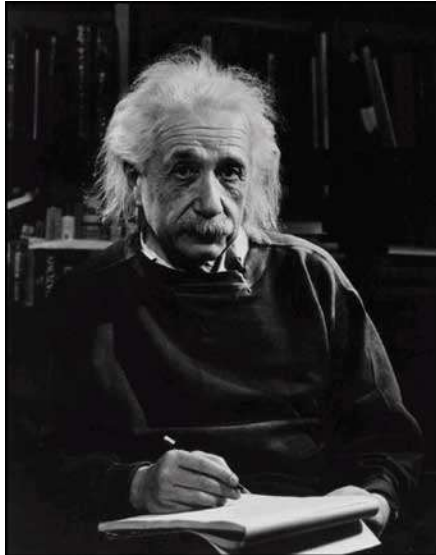
# *Human Vision*

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- Can do amazing things like:
  - Recognize people and objects
  - Navigate through obstacles
  - Understand mood in the scene
  - Imagine stories
- But still is not perfect:
  - Suffers from Illusions
  - Ignores many details
  - Ambiguous description of the world
  - Doesn't care about accuracy of world

# Computer Vision

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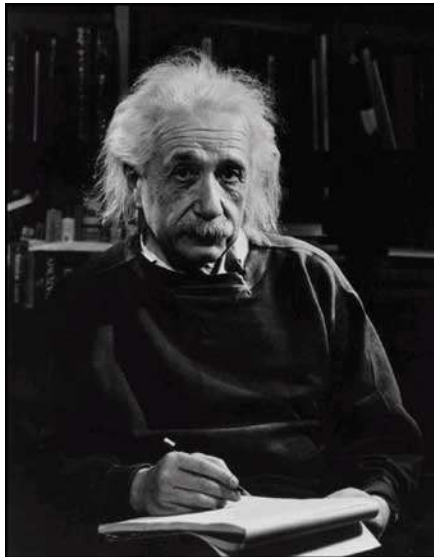
What we see

0	3	2	5	4	7	6	9	8
3	0	1	2	3	4	5	6	7
2	1	0	3	2	5	4	7	6
5	2	3	0	1	2	3	4	5
4	3	2	1	0	3	2	5	4
7	4	5	2	3	0	1	2	3
6	5	4	3	2	1	0	3	2
9	6	7	4	5	2	3	0	1
8	7	6	5	4	3	2	1	0

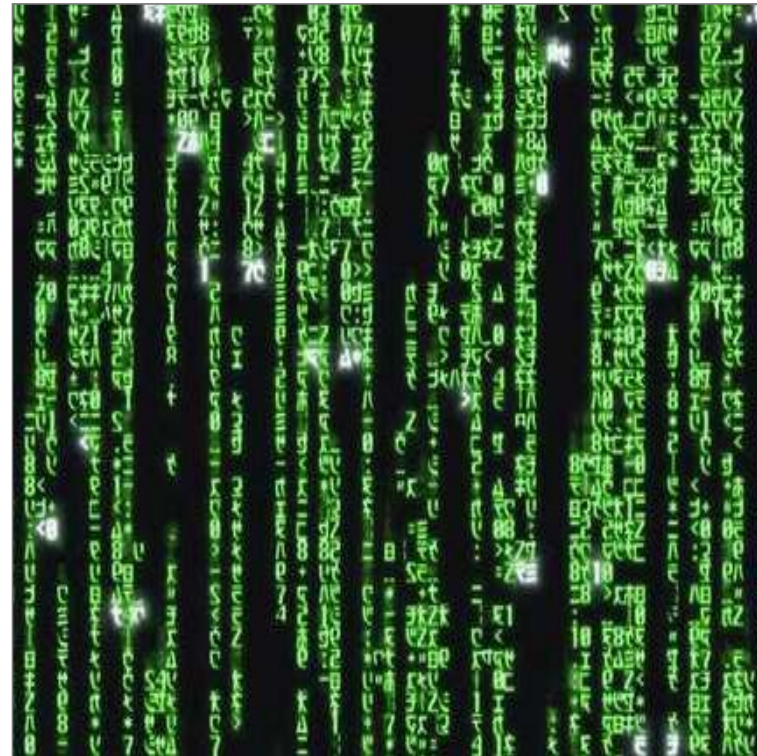
What a computer sees

# Computer Vision

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What we see



What a computer sees

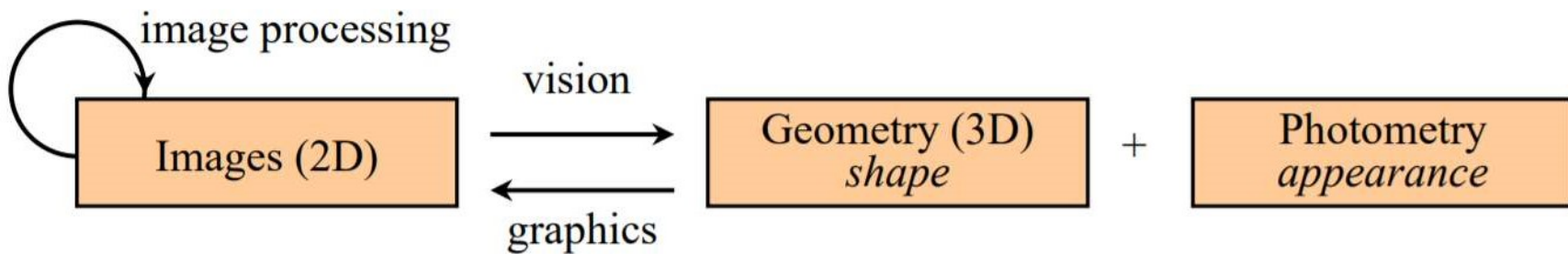
# *What is computer vision?*



*Terminator 2*

# *What is Computer Vision?*

- Computer Vision
  - Inverse problem: Hard
  - Image Processing
- Graphics
  - Forward problem





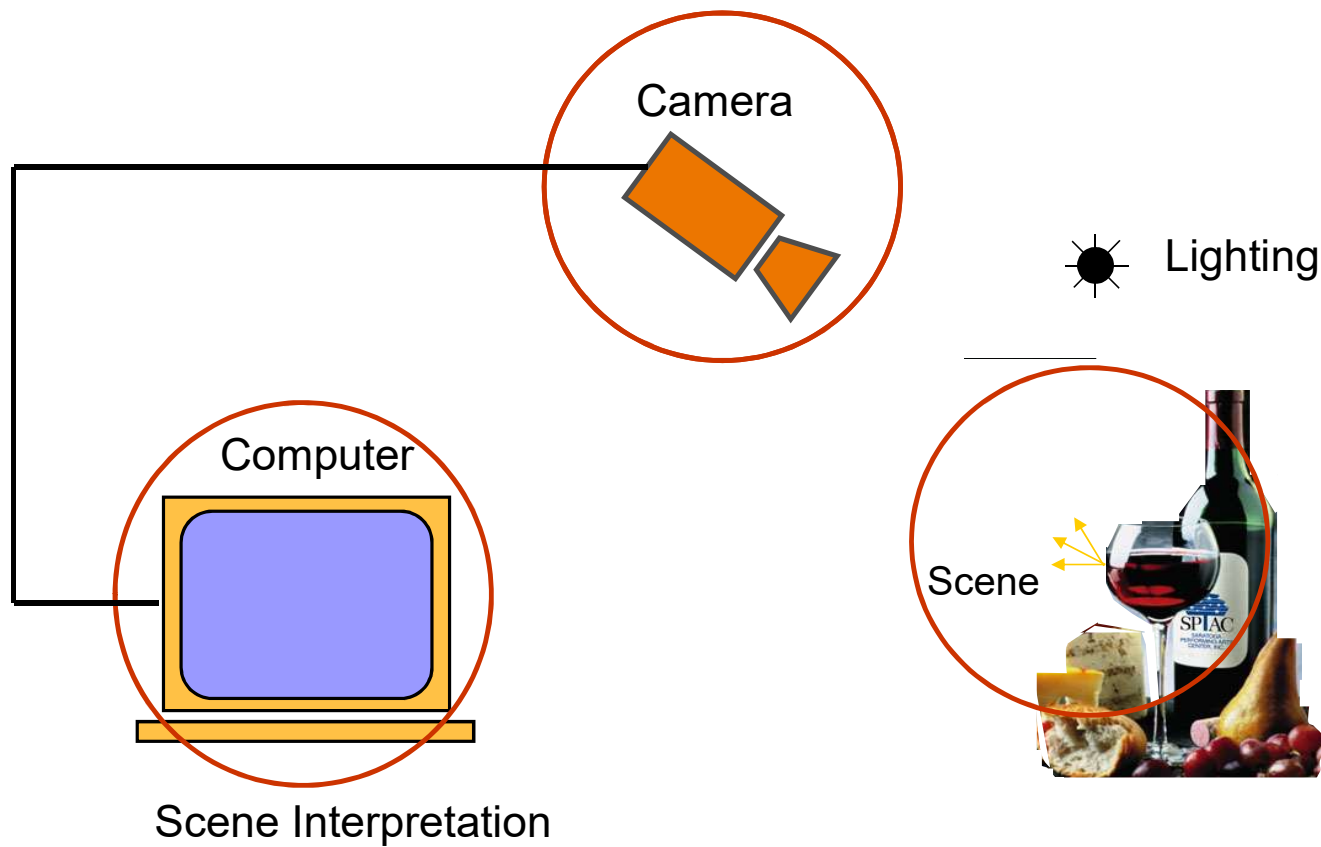
# *What is Computer Vision?*

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- Inverse Optics
- Intelligent interpretation of Imagery
- Building a Visual Cortex
  
- No matter what your definition is...
  - Vision is hard.
  - But is fun...

# Components of a Computer Vision System

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## *Every picture tells a story*



- Goal of computer vision is to write computer programs that can interpret images

## *Can computers match (or beat) human vision?*

- Yes and no (but mostly no!)
  - humans are much better at “hard” things
  - computers can be better at “easy” things



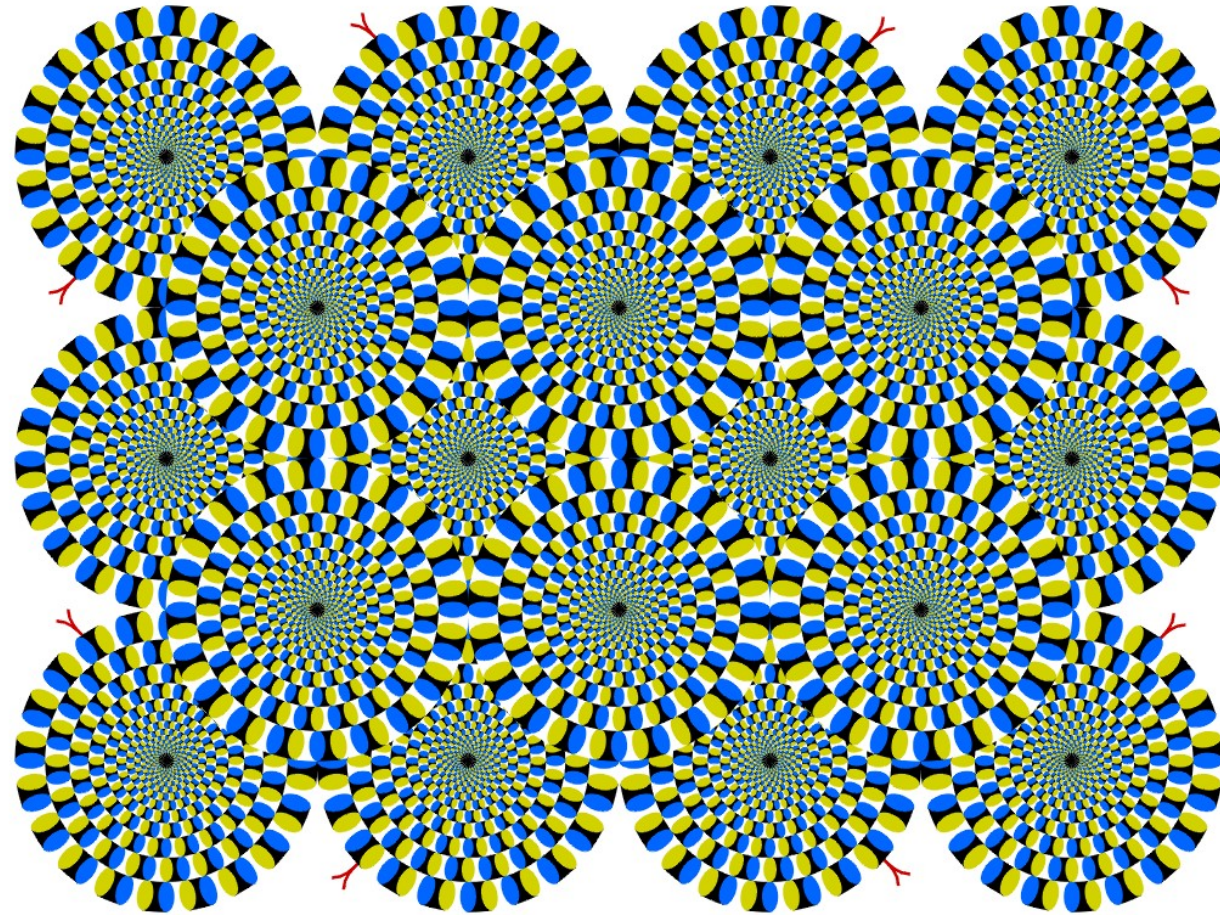
*Human perception has its shortcomings...*



[Sinha and Poggio, \*Nature\*, 1996](#)

*Is this image in motion?*

- Look at the image as a whole. Are the wheels in motion?
- Now focus on one wheel in particular. Is that one in motion?

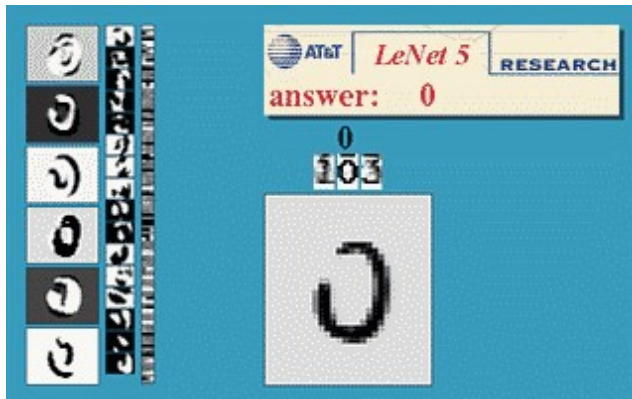


# *Some Topics in Computer Vision*

# *Optical character recognition (OCR)*

Technology to convert scanned docs to text

- If you have a scanner, it probably came with OCR software



Digit recognition, AT&T labs

<http://www.research.att.com/~yann/>



License plate readers

[http://en.wikipedia.org/wiki/Automatic\\_number\\_plate\\_recognition](http://en.wikipedia.org/wiki/Automatic_number_plate_recognition)



## *Face detection*

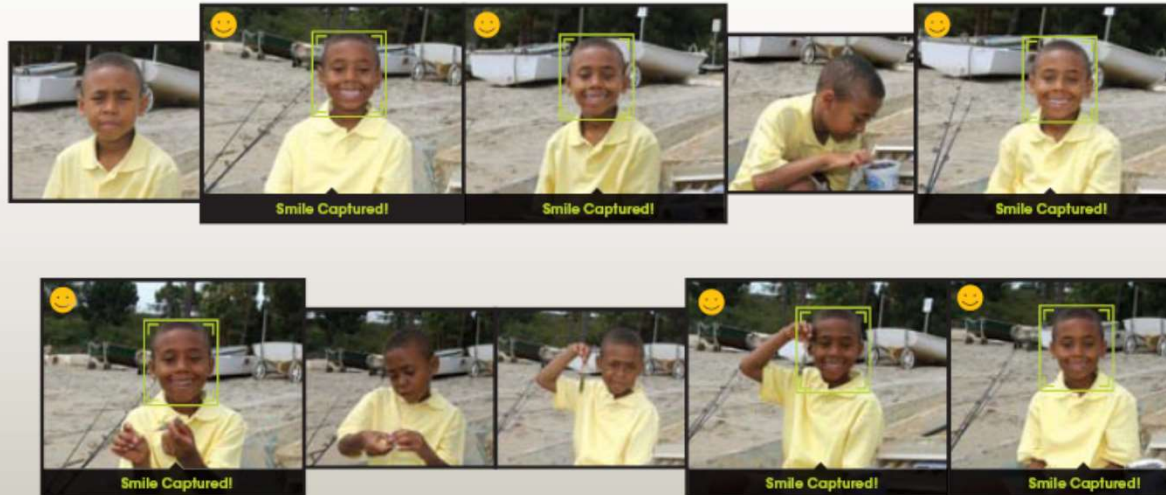


- Many new digital cameras now detect faces
  - Canon, Sony, Fuji, ...

# Smile detection?

## The Smile Shutter flow

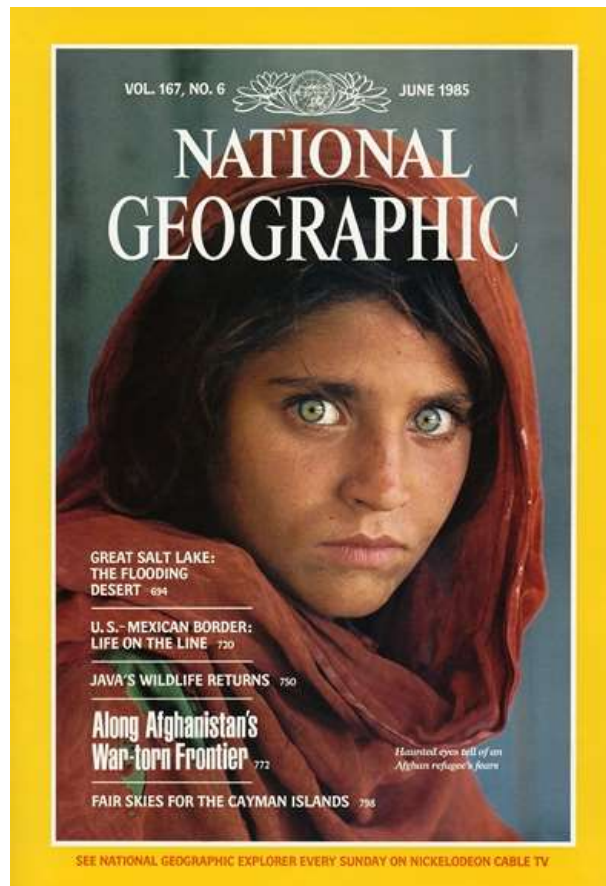
Imagine a camera smart enough to catch every smile! In Smile Shutter Mode, your Cyber-shot® camera can automatically trip the shutter at just the right instant to catch the perfect expression.



[Sony Cyber-shot® T70 Digital Still Camera](#)

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# Face recognition



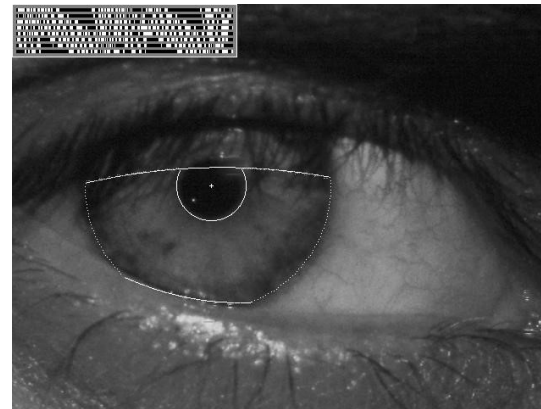
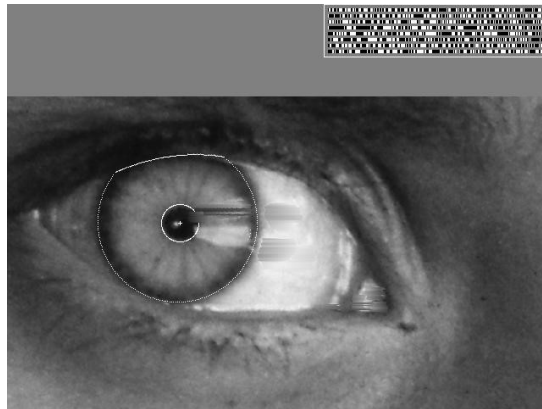
Who is she?

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## *Vision-based biometrics*



*“How the Afghan Girl was Identified by Her Iris Patterns”* Read the [story](#)



# *Login without a password...*



Fingerprint scanners on many new laptops, other devices



Face recognition systems now beginning to appear more widely  
<http://www.sensiblevision.com/>

# Object recognition (in mobile phones)



- This is becoming real:
  - **Lincoln** Microsoft Research
  - [Point & Find](#), [Nokia](#)
  - [https://www.google.com/intl/en\\_us/insidesearch/features/images/searchbyimage.html](https://www.google.com/intl/en_us/insidesearch/features/images/searchbyimage.html)

## *Shape and Morphology: Deformable Models*



*The Matrix* movies, ESC Entertainment, XYZRGB, NRC

Slide content courtesy of Amnon Shashua

## Smart cars

manufacturer products consumer products

### Our Vision. Your Safety.

rear looking camera forward looking camera side looking camera

EyeQ Vision on a Chip  
read more

Vision Applications  
Road, Vehicle, Pedestrian Protection and more  
read more

AWS Advance Warning System  
read more

News

- Mobileye Advanced Technologies Power Volvo Cars World First Collision Warning With Auto Brake System
- Volvo: New Collision Warning with Auto Brake Helps Prevent Rear-end

all news

Events

- Mobileye at Equip Auto, Paris, France
- Mobileye at SEMA, Las Vegas, NV

read more

- [Mobileye](#)
  - Vision systems currently in high-end BMW, GM, Volvo models
  - By 2010: 70% of car manufacturers.
  - [Video demo](#)



## *Vision in space*



[NASA'S Mars Exploration Rover Spirit](#) captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

### Vision systems (JPL) used for several tasks

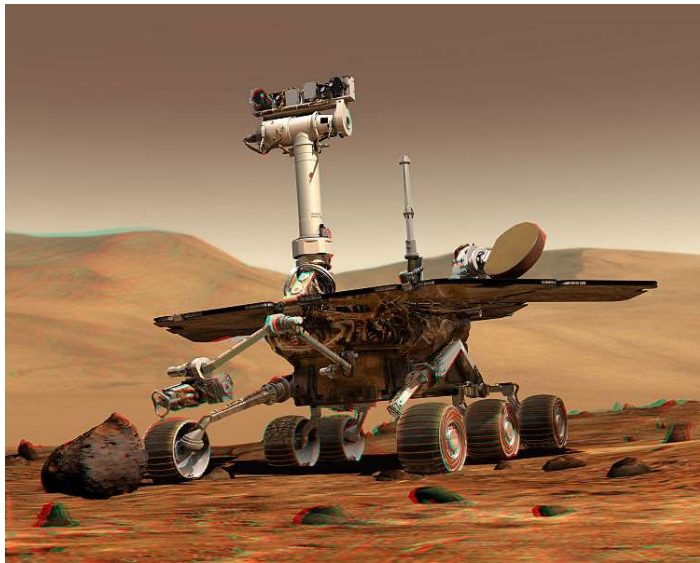
- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking
- For more, read "[Computer Vision on Mars](#)" by Matthies et al.

# *Delivery Robots: Starship Technologies and more*

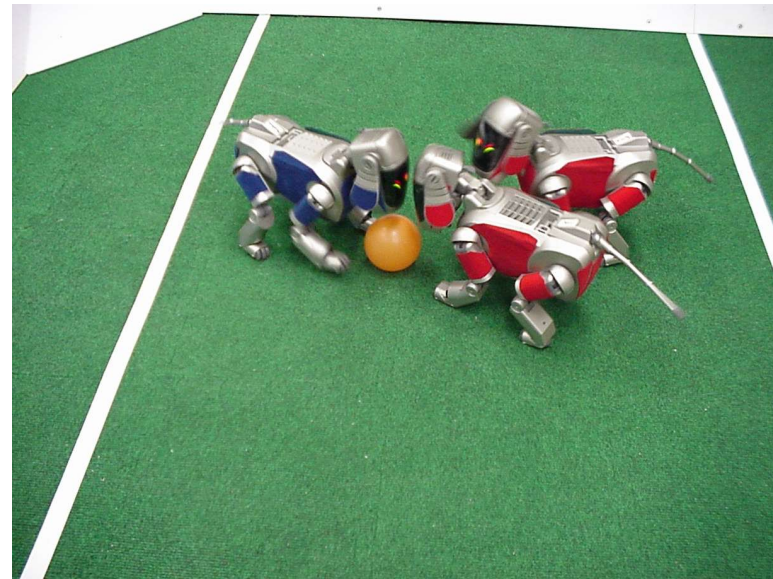
- **Computer Vision will transform the delivery industry**



# *Robotics*

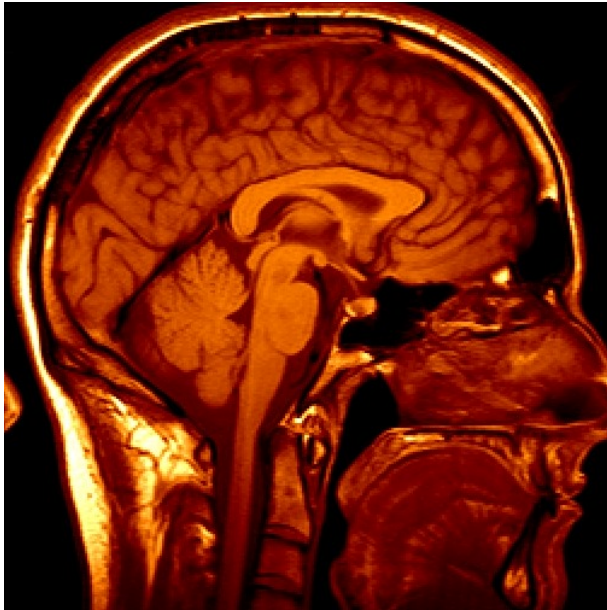


NASA's Mars Spirit Rover  
[http://en.wikipedia.org/wiki/Spirit\\_rover](http://en.wikipedia.org/wiki/Spirit_rover)



<http://www.robocup.org/>

# *Medical imaging*



3D imaging  
MRI, CT



Image guided surgery  
[Grimson et al., MIT](#)

## *Other Computer Vision Applications*

- Some industrial applications of computer vision:
  - automotive monitoring, car counting <http://www.mobileye.com/>;
    - <https://youtu.be/Y3ac5rFMNZ0?t=283>
  - Surveillance. Fight, Flight Detection / Target Tracking
    - <https://youtu.be/QcCjmWwEUgg>
    - <https://youtu.be/InqV34BcheM>
  - Sports Data: <https://www.secondspectrum.com/>
  - Morphing:
    - [https://youtu.be/pqpS6BN0\\_7k](https://youtu.be/pqpS6BN0_7k)
    - <https://youtu.be/nUDIoN-Hxs>

## *Current state of the art*

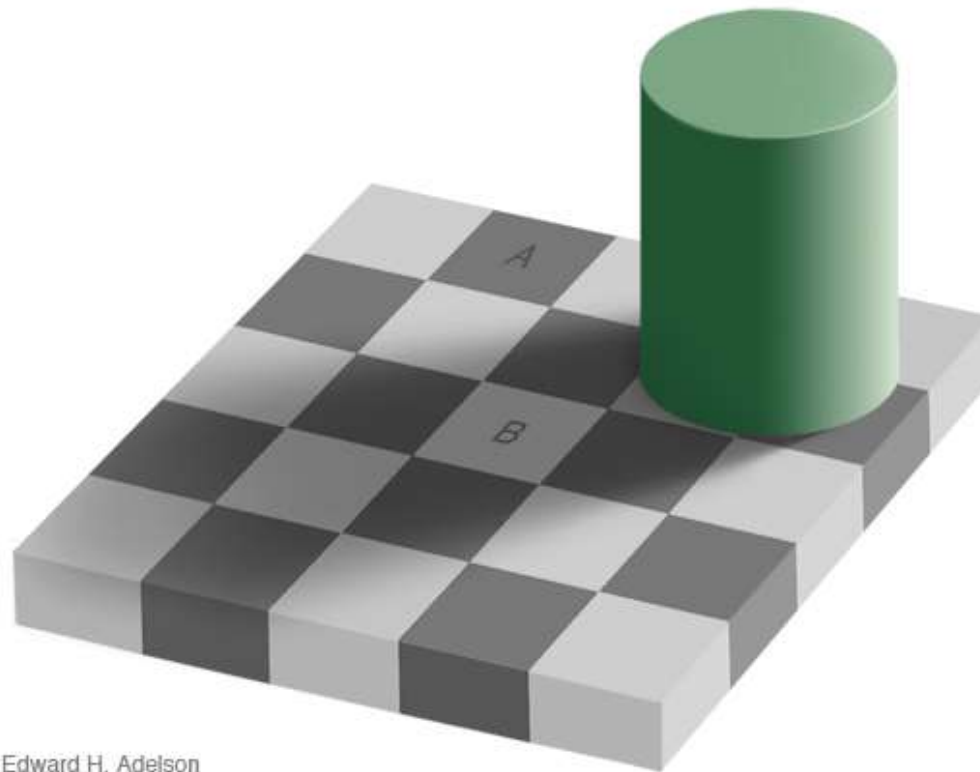
- You just saw examples of current applications.
  - Many of these are less than 5 years old
- This is a **very active** research area, and **rapidly changing**
  - Many new apps in the next 5 years
- To learn more about vision applications and companies
  - David Lowe maintains an excellent overview of vision companies
    - <http://www.cs.ubc.ca/spider/lowe/vision.html>

## *Topics covered*

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# *Lightness and Perception*

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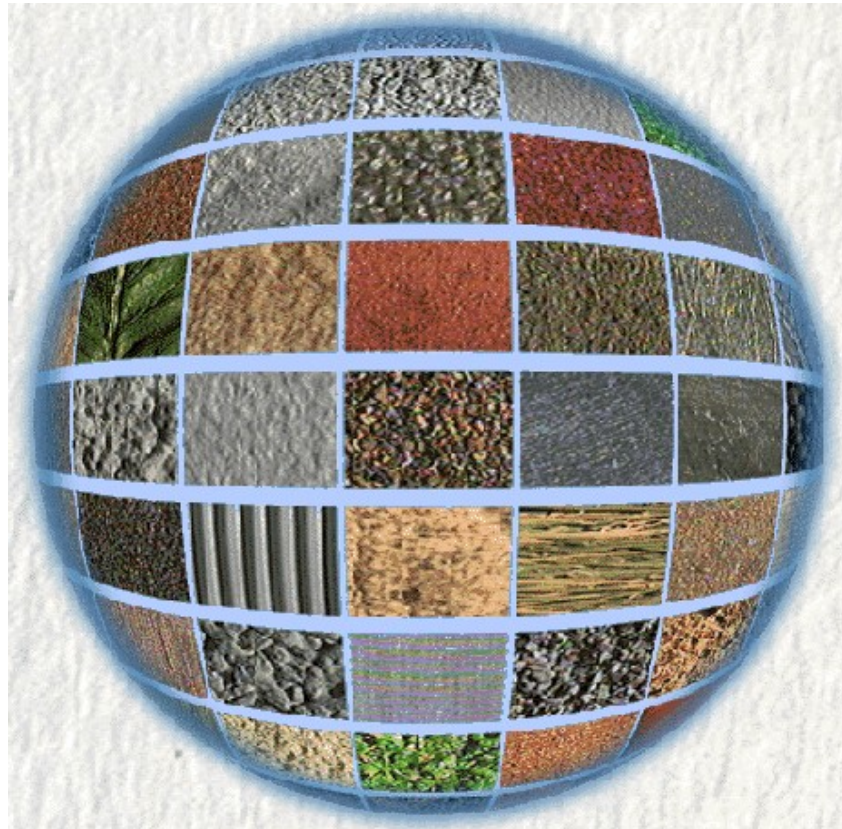


Edward H. Adelson

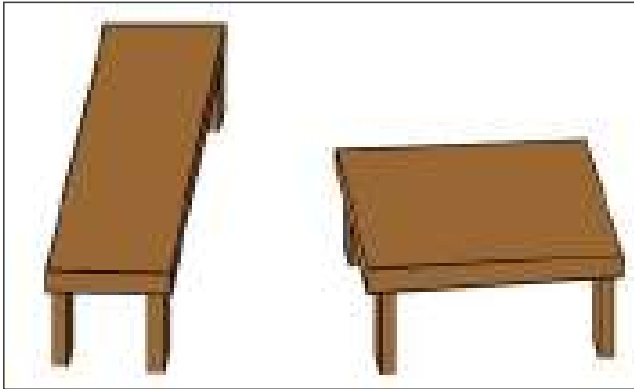


# Surface Reflectance

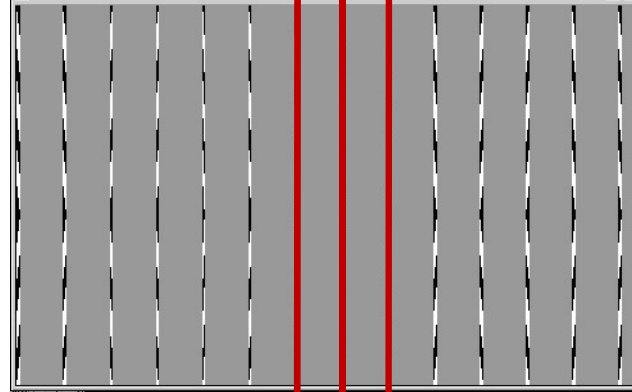
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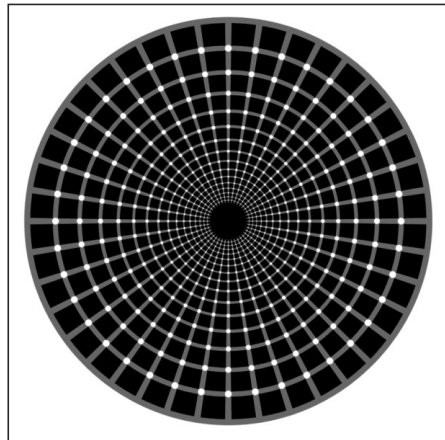
# Human Vision: Optical Illusions



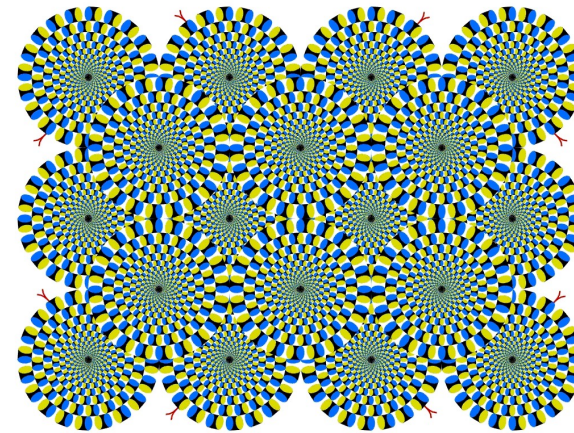
Which is bigger?



Straight Lines?



Dots White? Or Black?



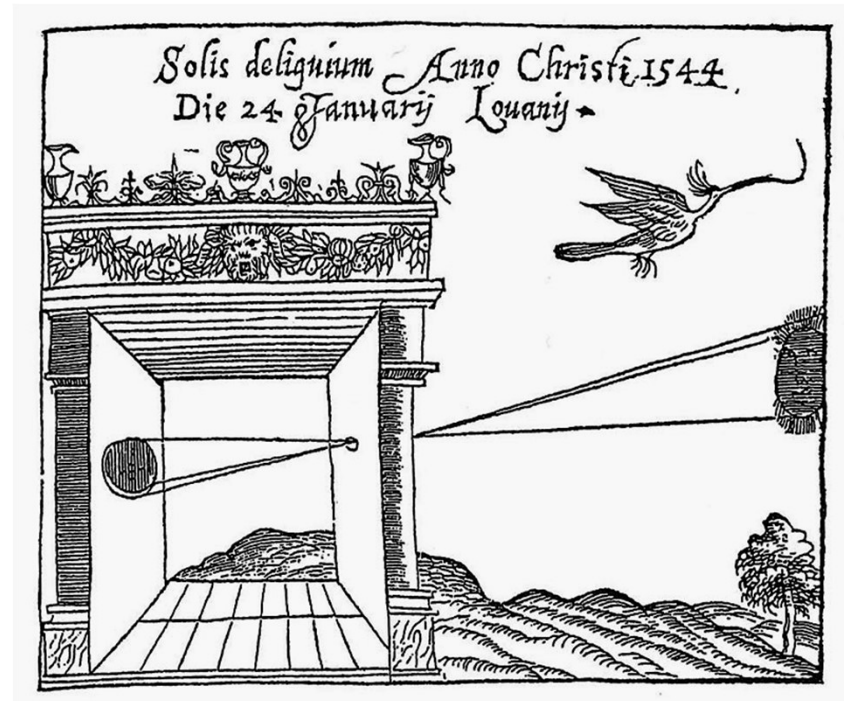
Spinning Wheels?

# Cameras and their Optics

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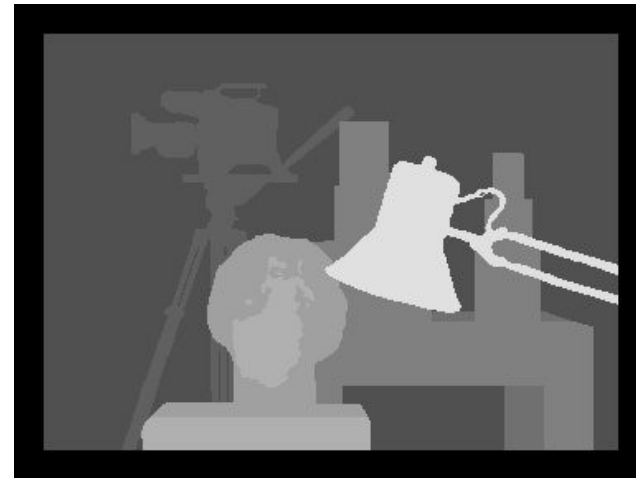
Today's Digital Cameras



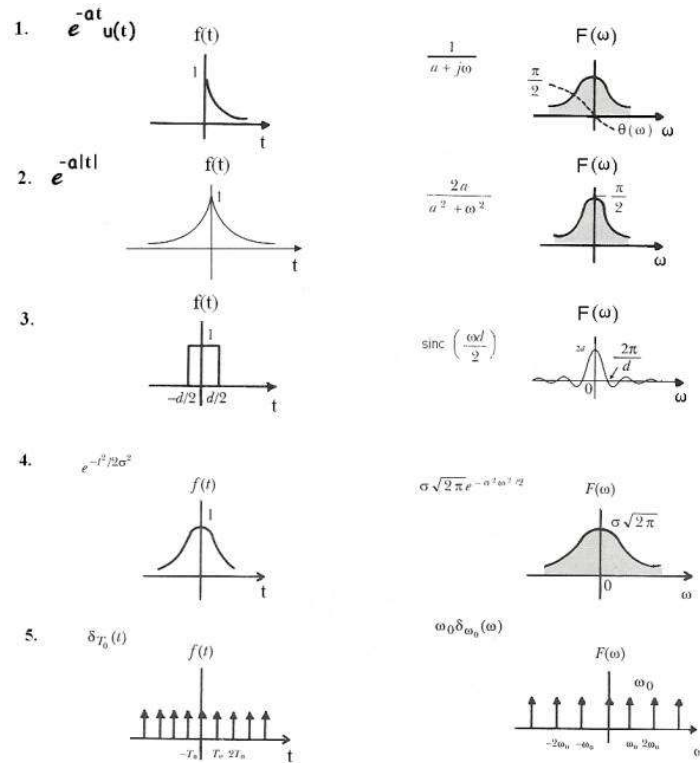
The Camera Obscura

# *Binocular Stereo*

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# Image Processing

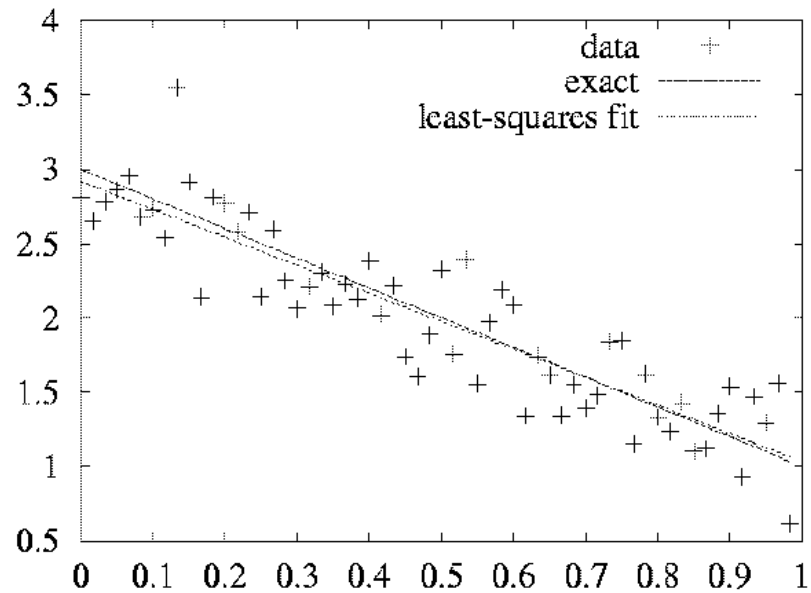


Fourier Transform  
Sampling, Convolution

Image enhancement  
Feature detection

# Statistical Techniques

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Least Squares Fitting

## *Face detection*

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# Face Recognition

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- Principle Components Analysis (PCA)
- Face Recognition



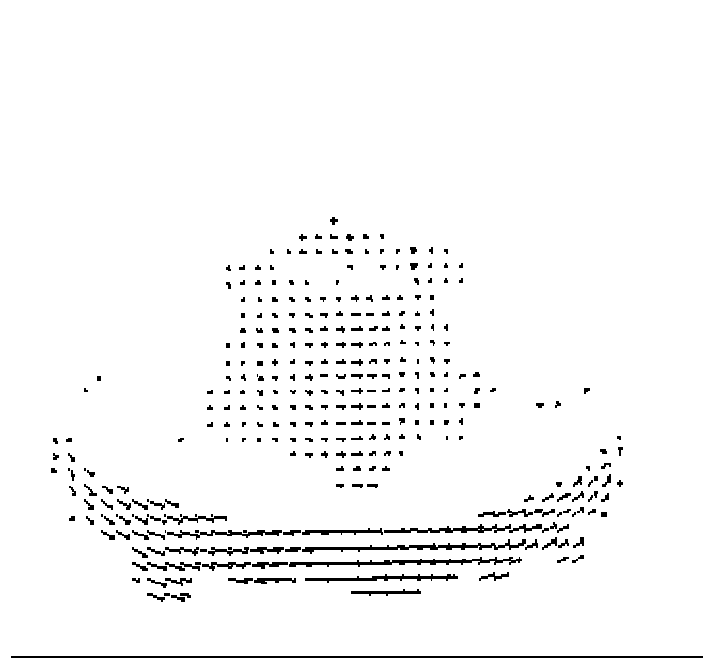
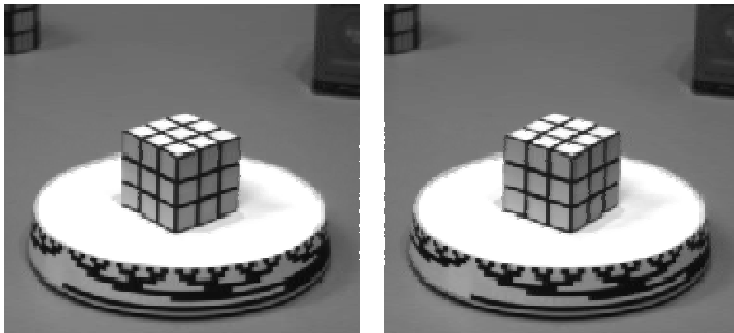
# Tracking

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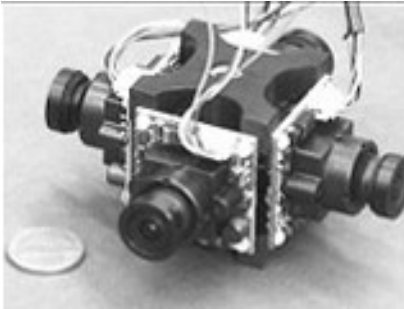
# *Optical Flow*

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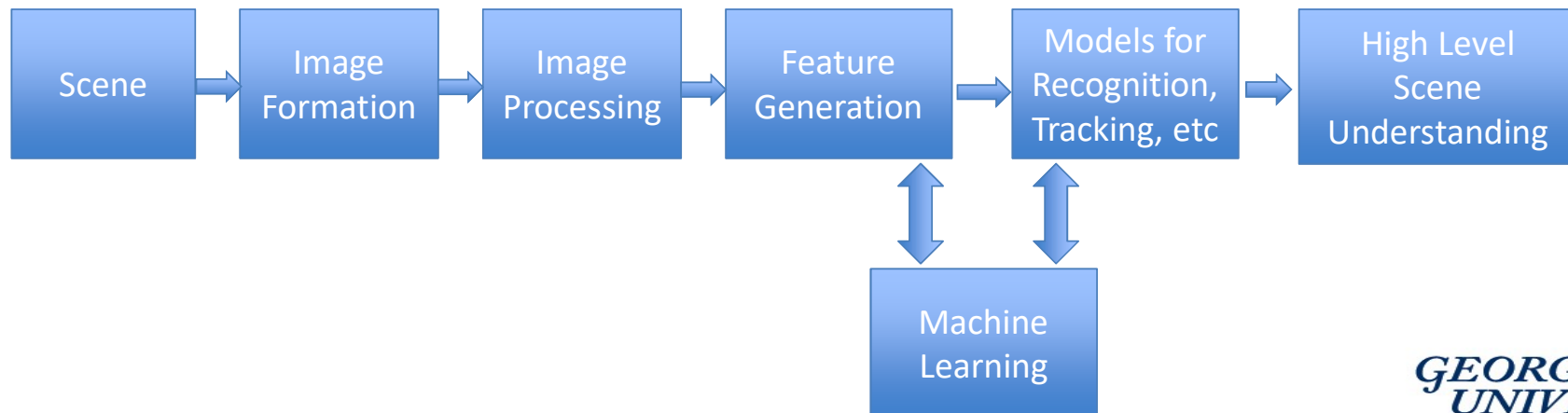
## *Some Recent Trends in Vision*

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## *Computer Vision ... the journey*

- Attaining scene understanding is a long journey
- Our course will largely develop these concepts in their intuitive order



# *Appendix*

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